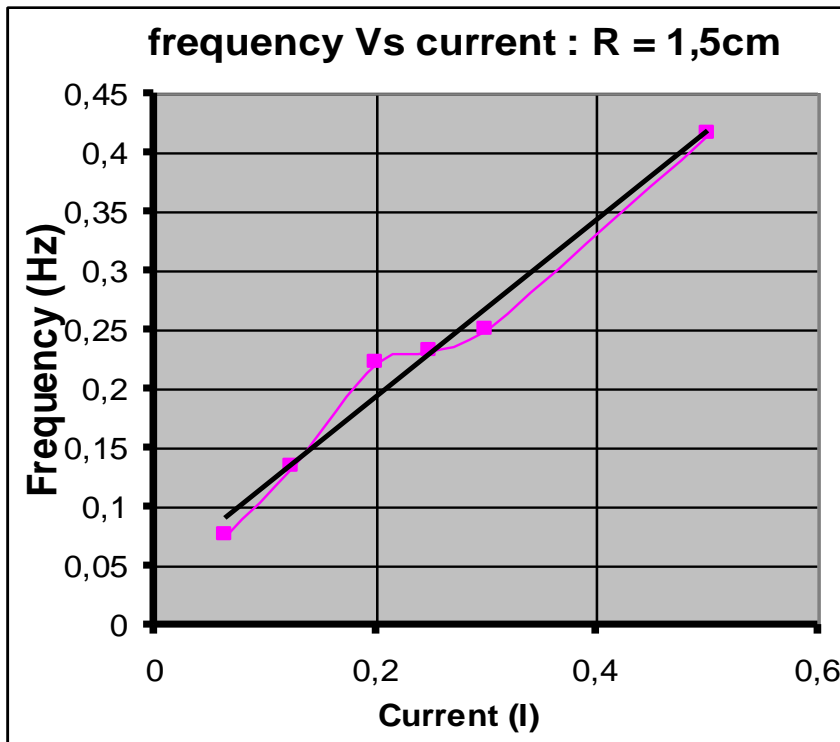


# Ionic Motor

# Experiences

- 1mol/L natrium chlorid solution
- small magnet or Helmholtz coils
- for different currents and different radius, we measure the solution's speed
- we made a model
- we compared the model predictions and the measurements

# Dependance speed - current



- The speed is proportionnal to the current (moving charges)
- The speed is smaller for a bigger radius

# Model

- 3 Forces

- electrical :  $\mathbf{F}_e = q \mathbf{E}$

- Magnetic :  $\mathbf{F}_m = q \cdot \mathbf{V} * \mathbf{B}$

- Friction :  $\mathbf{F}_f = -f \cdot \mathbf{V}$

- Equation :  $m \mathbf{A} = \mathbf{F}_e + \mathbf{F}_m + \mathbf{F}_f$

- System : one charge + from center to border or one charge - from border to center

# Electric field E

- This field is not uniform
- We can show that this field is dependant of the radius :

$$E(r) = \frac{U}{\text{Ln}\left(\frac{R2}{R1}\right)} \times \frac{1}{r}$$

# The Magnetic force

- **The solution speed is not the charge speed :**
  - solution speed :  $10^{-2}$  to  $10^{-1}$  m/s
  - electrical force :  $qE \sim 1.6 \cdot 10^{-19} \cdot 100 \sim 10^{-17}$  N
  - Magnetical force : if speed  $\sim 10^{-2}$  m :
    - $qv_b \sim 1,6 \cdot 10^{-19} \cdot 10^{-2} \cdot 10^{-2} \sim 10^{-25}$  N
  - the 2 forces are too different and if the charge had the same speed as the solution, the friction force would be zero

# Computer simulation

Radius1	Radius2	Tension	charge	MasseA	MasseB	Magnet	Coef_fr	dt
0,01m	0,05m	5V	1,6E-19C	4E-26Kg	4E-26Kg	0,01T	1E-20N.s/n	1e-6s

$$A_x \leftarrow \frac{1}{m} \cdot \left( q \cdot \frac{U}{r \cdot \ln\left(\frac{R2}{R1}\right)} \cos(teta) + q \cdot B \cdot Vy - f \cdot Vx \right)$$

$$A_y \leftarrow \frac{1}{m} \cdot \left( q \cdot \frac{U}{r \cdot \ln\left(\frac{R2}{R1}\right)} \sin(teta) - q \cdot B \cdot Vx - f \cdot Vy \right)$$

$$Vx \leftarrow Vx + Ax \cdot dt$$

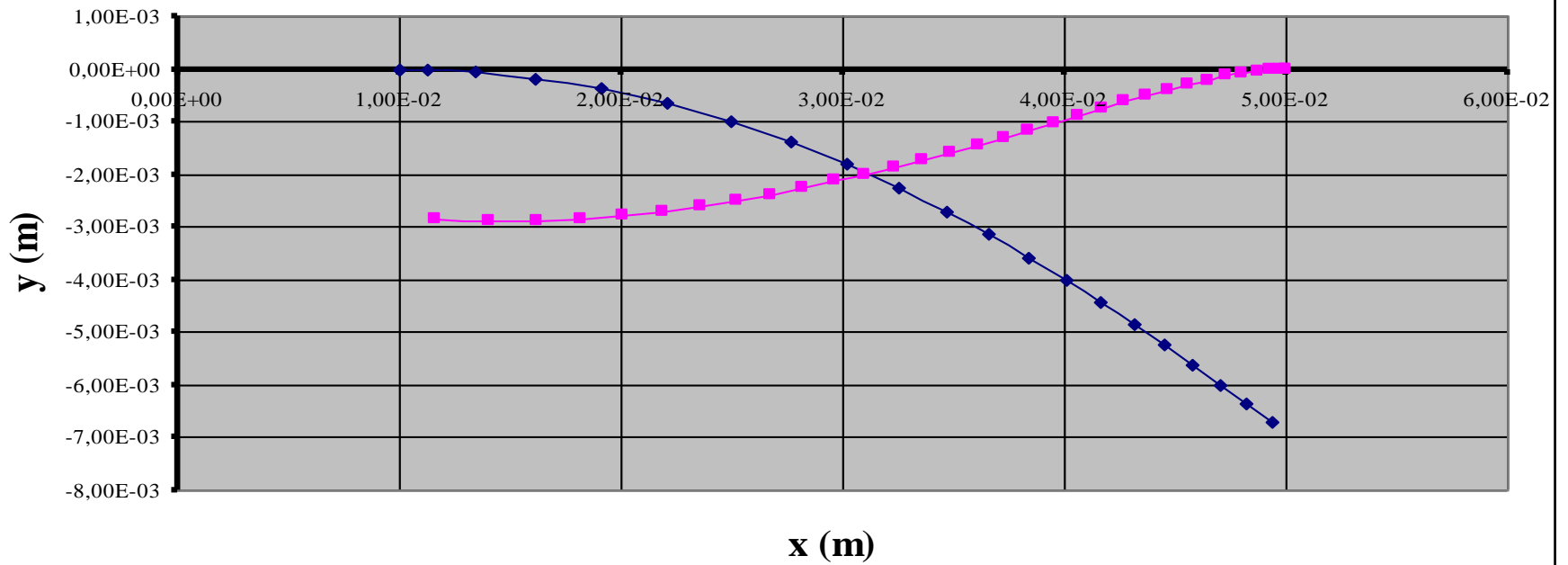
$$Vy \leftarrow Vy + Ay \cdot dt$$

$$x \leftarrow x + Vx \cdot dt$$

$$y \leftarrow y + Vy \cdot dt$$

# Path of charges + and -

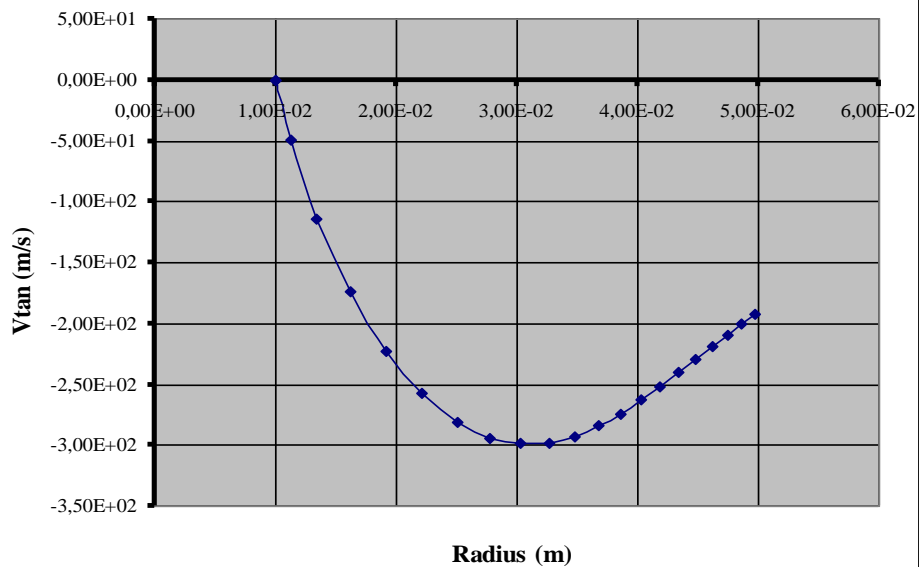
**Path**



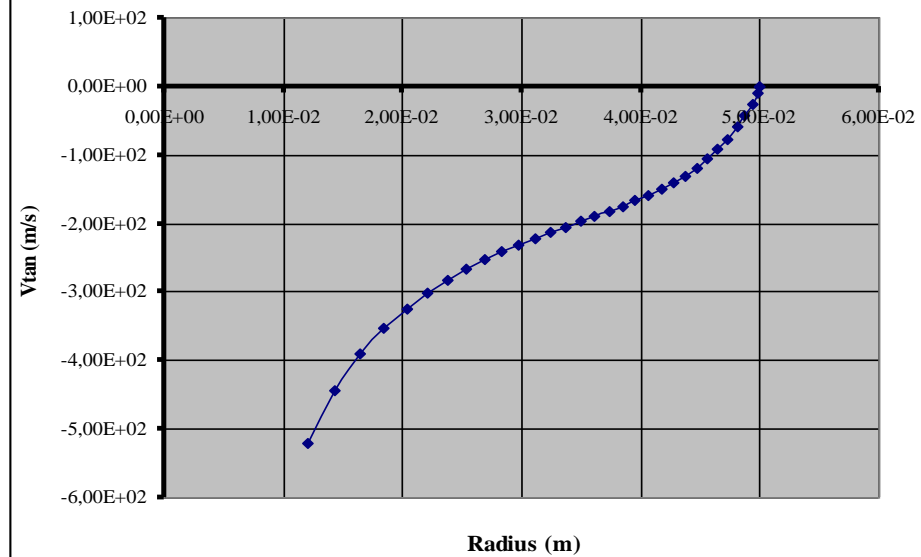


# Lateral Velocities

Vtan for + charge (in -> out)



Vtan for - charge (out -> in)

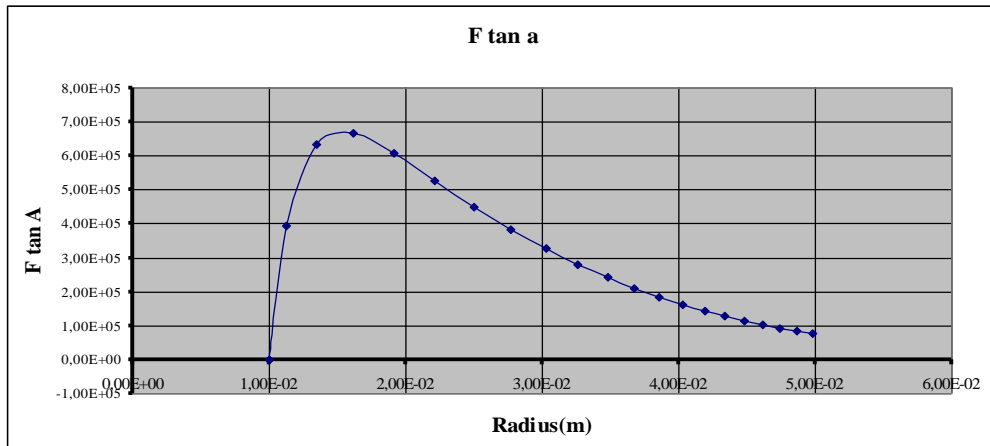
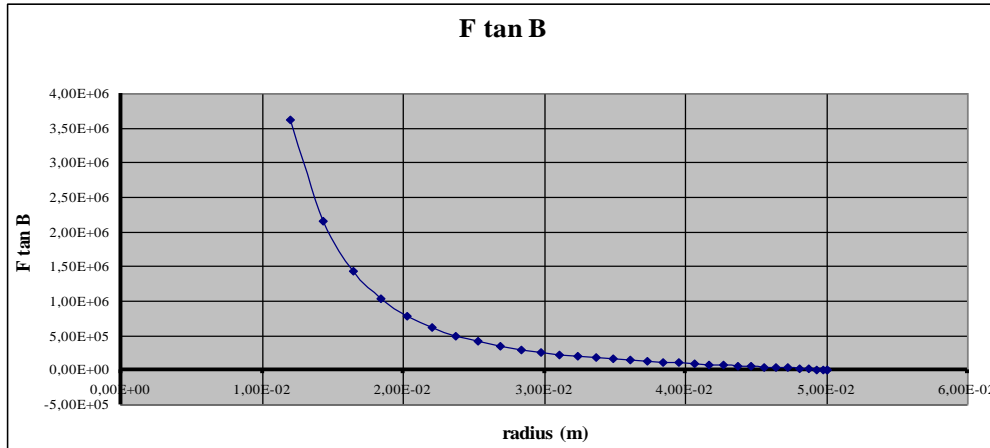


# Friction force

- The friction force is proportional to the velocity
- it is also proportional to the charge density, that means inverse proportional to  $r^2$

$$F = k \cdot \frac{V}{r^2}$$

# Force causing the solution 's movement (1/2)



# Force causing the solution 's movement (2/2)

